1. Install antenna mount and Battery anti-slip mat

Screw the antenna fixing mount and put the antenna sleeve into the fixing mount. Then use some hot melt glue to fix the antenna sleeve.



2. Specification
Brand Name: Eachine
Item Name: Novice-IV 3-4S 4inch LR drone and RTF
Wheelbase: 170mm
Size: 180mm*130mm*40mm(without propellers,batteries,antenna)
Weight: 125g (without battery)
3. Features
The lightest 4inch LR FPV drone
New AIO Flight controller with 25A ESC
Efficiency 1404 KV2750 brushless motor
Long flight time around 20minutes with stock battery Sub 250gram
Around 31minutes flight time with 4s 18650 3000mah
Very stable and easy to control
With M8N GPS Rescue system
With Buzzer and LED drone tracker finder
Distance Range more than 1KM in an Open area without interference



4. Advanced function description

DT-B90 Buzzer&LED Finder how to work?

1. DT-B90 Finder can power itself to beep and LED light to flash even the quad battery has been ejected.

- 2. Press the button for 2 or 3 seconds to turn on it before flying
- 3. You can use AUX4(SF Switch) channel to activate the Buzzer

4. You need to Press the button for 2 or 3 seconds to turn off it after disconnect the main battery.

Eachine M8N GPS rescue function how to work?

1. Before Armed, GPS must search for more than 6 satellites to lock the home position.

2. After armed, observe the OSD data during the flight, and the rescue function can work normally only if the distance exceeds 100 meters. Otherwise, the quad will crash. If the remote controller suddenly loses signal, the GPS rescue

function will work automatically and return to the home position, but the drone won't land automatically. You need to slightly control the stick to gain control of the drone when the remote control signal is restored and then control the drone to land.

3. In order to avoid mistake operation , we didn't enable Aux Channel to activate the GPS rescue function by default. You can set it by yourself from the mode tab of Betaflight configurator.

5. Start FPV Flight

Install the antenna to the radio and the goggle first. And then powering on your Radio and goggle. NOVICE-IV comes already bound to your radio and on the right video channel matched with your goggles. Power the battery is plugged in, set NOVICE-IV on a stable surface so it can calibrate.Calibration takes a few seconds then NOVICE-IV is ready to fly. Please fly in open areas and away from the crowd and buildings.



1.Install the battery to the radio(shows on picture A), and turn on the "power switch", Press any key to skip if any alarm(show on the Picture B) appear on the screen



2.Connect the battery to the NOVICE-IV Drone, and make sure to fixed the battery properly with the Lipo strap.



3.Turn on the EV800DM Goggles, check the video and the status of the oSD info , Make sure GPS must search for more than 6 satellites to lock the home position .



4.Keep the throttle stick lowest point and then toggle the SE Switch to Arm the NOVICE-IV drone, you will find "ARMED" notice on the screen of the goggles. Happy flight and keep it safe.

Important notice:

The bellowing content are regard to advanced tutorial. The Novice-IV drone comes out already finished all the settings and bound with the radio . Need these content after you re-flashed the firmware or doing some troubleshoot.

7.Flight controller connection diagram





8.Binding procedure

 Press and hold the BIND button on the receiver then plug the USB to connect the power. After approximately 3 seconds, the Red LED on the receiver would be solid ,this indicate the receiver is in bind mode.

2. Select Frsky D8 protocol from the Multi mode and then press [BIND] option, the red LED on the receiver should blinking fast, this indicate bind is successful. Unplug the USB and then plug again, the red LED is solid means the connection with the radio is established.







5.Toggle the SB switch to change the flight mode(Default is Air mode).We highly recommend to use Angle mode for the beginners . The motors will auto-spin when armed if the flight mode is AIR MODE.

6.Charger the Lipo Battery



Charging Function After insert adapters, chargers "drop" sound, the display shows ;

Insert the battery charger "drip - drip" twice to start charging. Display cycles through each section

total battery voltage and the battery voltage;

After the battery is fully charged, the charger automatically stops charging, the display shows "FULL" And flashing, buzzer once every five seconds. Voltage Display Function Insert the battery (without connecting adapter),

6.Flight and Radio Stick Controls

Always use caution when flying and operate in an open and controllable area. Please learn the flight controls first before powering on the aircraft to fly. The left stick controls throttle and yaw direction of NOVICE-IV. The right stick controls pitch and roll of the aircraft.

Left Stick Diagram



Right Stick Diagram



9.Receiver configuration

Please enable Serial RX for UART6 from port tab, then set Receiver mode to be Serial-based receiver from the Configuration tab of the Betaflight Configurator, then select SBUS protocol for the Serial Receiver Provider.

USETT 11520 • Deabled • AUTO • Deabled • AUTO • UTX (TBS 5m • AUTO • ual12 115200 • Deabled • AUTO • CPS • 57600 • Deabled • AUTO • upp13 115200 • Deabled • AUTO • Deabled • AUTO • Deabled • AUTO •		+ LAUTO	Provide and the						
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Receiver Senal-based receiver (SPEKSAT, 5 • Receiver Mode						Receiver Mode	SPEKSAT,	2000	1222000000

10.VTX Bands and Channels setup



There are 3 ways to switch the vtx channels:

1.Short press the switch button to choose the VTX channel, press and holding

the button to Choose the VTX Band (Can't save , it will lost the channel while power off) 2.Go to Betaflight CLI ,type the command:

Set vtx band=3

Set vtx_channel=1

save

Notes: The vtx_freq should match the vtx_band and vtx_channie as the VTX Channel list shows.

For example, if you set vtx_freq=5732, you should set vtx_band=5 and VTX_channel=3

3.Enable Smartaudio for UART1, then move the stick of the transmitter (THR MID+ YAW LEFT+ PITCH UP) to enter OSD Menu, Enter to Features, then enter to VTX SA to set VTX Band and channel

115200 * 0 Disabled . AUTO . Disabled . AUTO . Disabled · AUTO · (ART) (115200) Disabled + AUTO + Disabled . AUTO . VTX (TBS Smi + AUTO + UART2 115200 • Disabled . AUTO . • 57600 • · AUTO . 0 GPS Disabled Disabled . AUTO . Disabled . AUTO . + AUTO + UARTS 115200 • (1) Disabled 115200 • Disabled + AUTO + Disabled + AUTO + Disabled · AUTO ·



Butto	ons and	ports		1		3	K	1
1)CH	+/Bamd+		4			() (8)	9	
		is button	salact Ci	H 1 - 8 cv	-105			
	•	nd RETU						
		boot/shu						
-	-	ring work		turn				
3)SRC	MENU							
Short	press to	select fr	om video	sources	V-in/RF	A/RF B/	Diversity	
Long	press to	call out N	IENU					
4)SEA	RCH							
Press	to auton	natically s	search fo	r the sig	nals;			
	ARGING I							
		e range r	echargin	g port/po	ower bac	kup port,	typically	@5V/2A;
6)RES								
		ut down d	evice wh	en neces	sary;			
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9)Pic	-	v m mou	e,Auulo t	utputen	r moue,			
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	•	start reco			•		save vid	eo.
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press) as-set	tings.				•	Ũ	•
Charg	ing indic	ator LED	chargin:	g-red;ful	l charged	-green.		
D	0114	0.116	0.116		0115	011/	0.117	0.110
Band A	CH1 5865	CH2 5845	CH3 5825	CH4 5805	CH5 5785	CH6 5765	CH7 5745	CH8 5725
B	5733	5752	5771	5790	5809	5828	5847	5866
E	5705	5685	5665	5645	5885	5905	5925	5945
F	5740	5760	5780	5800	5820	5840	5860	5880

11.Goggles and VTX Receiver channel setting

12.Mixer type,ESC/MOTOR protocol and Sensor alignment

5658 5695 5732 5769 5806 5843 5880 5917

R



DSH	IOT6	00	ESC/Mator protocol	0		
0	Ð	MOTOR_STOP	Don't spin the motors when armed			
Oli	Ð	ESC_SENSOR	Use KISS/BLHeli_32 ESC telemetry over a separate wire			
	D	Bidirectional DShot	t (requires supported ESC firmware)	0		
12	\$	Motor poles (numb	Motor poles (number of magnets on the motor bell)			
5.5	\$	Motor Idle Throttle	Value [percent]	0		

00	Roli Degrees	9 0 ‡	Pitch Degrees	Yaw Degrees
First 🔹	GYRO/ACCEL	CW 180' ¥	FIrst GYRO	



13.GPS and GPS Rescue settings

GPS	
GPS GPS for naugation and telemetry	0
Note: Remember to configure a Serial Port (via Ports tab) when using GPS feature.	
UBLOX Protocol	
Auto Baud	
Auto Config	
Use Galileo	0
Set Home Point Once	0

) GI	PS R	lescue
35	÷	Angle
100	÷	Initial altitude (meters)
100	\$	Descent distance (meters)
15.00	\$	Ground speed (meters/second)
1100	\$	Throttle minimum
1600	\$	Throttle maximum
1280	\$	Throttle hover
5.00	\$	Ascend rate (meters/second)
1.50	\$	Descend rate (meters/second)
6	\$	Minimum satellites
		Allow arming without fix - WARNING: the GPS Rescue will not be available

14.Radio channels/Switch and Betaflight mode setting





15.ESC Check and Flash firmware

1.Download New release Bihelisuite from:

https://www.mediafire.com/folder/dx6kfaasyo24l/BLHeliSuite 2.Connect the NOVICE-IV flight controller to computer



3.Open the Device Manager of your computer, find the Ports, please make sure the Com port Serial Number is under 255, otherwise it will can't connect to the BLHELISUITE. You can change the port serial number like the bellowing step :

Hant A Network P Ports TT S	ors ork adapters (COM & LPT)	M Part (COM436			Port Settings	Octails	27-312A)
🛞 🚇 Syste	d, video and m devices	gane controller a controllers	5			Bta	per second: 5600 Data bits: 0	2 2
vanced Settings for COMA Set FIFO buffers (eq Select lower entings (Select loyler antings)	uims 16550 (n comect con	necton problem				OK Cancel Defaults	C Party: None Rop bits 1 r control: None Advanced	E E Bestore Defaults
Beceive Buffer: Cow (1)	1		0	—1 s	gh (14) (14)	- 20 datas		<u> </u>
Janamit Buffer: Low (1)	S.	-	to:	_ a	\$19 (19)			
COM Bott Number: COM25								OK Canor

4.Open the BLHELISUITE, Select SILABS BLHeli Bootloader (Cleanflight) from the third tab on the top side. Then Select the right Serial com port and Click connect. You can also Flash the new release BLHeli_s firmware via the BLHEILISUITE, the firmware Target is "F-H-40"



16.Flight controller firmware update

1.Install latest STM32 Virtual COM Port Driver

http://www.st.com/web/en/catalog/tools/PF257938

2.Install STM BOOTLOAD Driver (STM Device in DFU MODE)

3.Open Betaflight configurator and choose firmware target "BETAFLIGHTF4", then select the firmware version.

4. There are 2 ways to get in DFU Mode: 1). Press_and_hold_the_boot_button, then plug USB to computer 2).loading betaflight firmware and hit "flash", then it will getting into DFU Mode automatically.

5.Open Zadig tools to replace the drivers from STM32 Bootloader to WINUSB Driver. 6.Reconnect the flight controller to the computer after replace driver done, and open Betaflight Configurator, loading firmware and flash.

Zadig	Options Help		0
STM32	BOOTLOADER		• Edr
Driver	STTub30 (v3.0.4.0)	WinUSB (v6. 1, 7600, 16385)	Hore Information WinUSB (Ibusb)
USB ID	0483 DF11		ibusb-win32
WCID ²	X	Replace Driver	BusbK WinUSE (Microsoft)