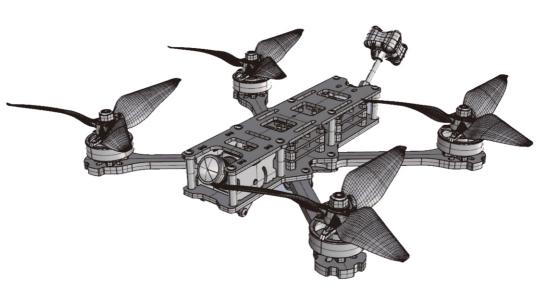
WIZARD X220HV

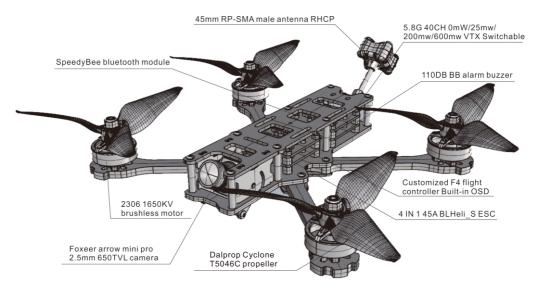
QUICK START GUIDE





Package included:

- 1 x X220HV frame kit
- 2 x 2306 1650KV brushless motor CW
- 2 x 2306 1650KV brushless motor CCW
- 1 x 4 IN 1 45A BLHeli S ESC
- 1 x Customized F4 flight controller Built-in OSD
- 1 x Foxeer arrow mini pro 2.5mm 650TVL camera
- 1 x 5.8G 40CH 0mW/25mw/200mw/600mw VTX Switchable
- 1 x 110DB BB alarm buzzer
- 1 x SpeedyBee bluetooth module
- 1 x 45mm RP-SMA male antenna RHCP
- 2 x 200*20mm battery strap
- 1 x 30° camera mount compatible with Runcam 3 3S Gopro session
- 2 x Dalprop cyclone T5046C transparent white CW
- 2 x Dalprop cyclone T5046C transparent white CCW
- 2 x Dalprop cyclone T5046C transparent purple CW
- 2 x Dalprop cyclone T5046C transparent purple CCW
- 10 x 2.5*100mm nylon strap black



Contents

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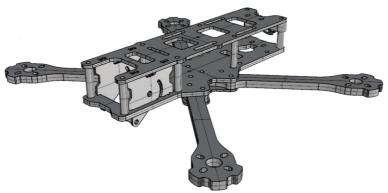


1.0 Frame kit

Wheel base: 220mm

Upper plate thickness: 2.0mm Frame arm thickness: 5.0mm Bottom plate thickness: 3.0mm X plate thickness: 1.5mm

Camera side plate thickness: 1.5mm Camera standoffs: M3*28mm 1 PC Frame standoffs: M3*20mm 8 PCS



2.0 Motor

Motor KV: 1650 RPM/V Idle current(Io/10V): 1.05A

Lipo cell: 3-6S Weight: 35g

Max continuous current: 36A Max continuous power: 860W

Max thrust: 2350g

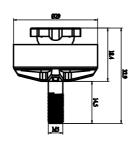
Configu-ration: 12N/14P Stator diameter: 23mm

Stator thickness: 6mm Motor diameter: 29mm Motor body length: 18.4mm Overall shaft length: 32.9mm Prop adapter shaft: M5

Bolt holes spacing: 16mm

Bolt thread: M3 Propeller: 5-6 inch







3.0 ESC

Integrated PDB

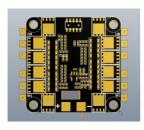
Working voltage: 2-6S Lipo

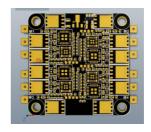
Continuous working current: 4*45A

Peak current: 4*50Å (6S)

Main control chip: 48Mhz EFM8BB2 Firmware: BLHeli S Supports Dshot600

MOS: 5*6





4.0 Flight controller

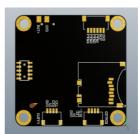
Main control chip: STM32F405

Sensor: MPU6000 6 axes

Power supply: 5V Integrated OSD LC filter on board

Supports BetaFlight / inva running firmware





5.0 Antenna

Brand name: Eachine Item name: antenna

Quantity: 1 PC

Conncetor: RP-SMA Male



6.0 Switchable VTX

Output power and transmission distance: ≥0.5km@25mW,

 \geq 1km to 200mW, \geq 2km to 600mW

Transmission power: 0mW / 25mW / 200mW / 600mW

Full video format: NTSC / PAL

Input voltage and power dissipation: 7V ~ 24V, + 12V /

260mA @ 600mW Size: 36*36*6mm

Weight: ≤ 7g (excluding antenna) With output power self-check function.

Nixie tube SCAN: frequency point (1-8), frequency band (AE),

power (1-3, 0=0mw, 1=25mw, 2=200mw, 3=600mw)

7.0 Camera

Solution: 1/3" Sony SUPER HAD II CCD + Nextchip 2040 DSP

Pixel: PAL: 976(H)x494(V)

TV system: PAL

Resolution: 600TVL(color) 650TVL(B&W)

Synchronization: internal Min.illumination: 0.01Lux

WDR: support

OSD programming board: support

White Dot repair: support

DNR: 2D DNR

Camera title: support

Image adjustment: support

OSD: Edit name, power, flying time

Input power: 5-40V

Storage temperature: -40° C \sim 60 $^{\circ}$ C Working temperature: -10° C \sim 50 $^{\circ}$ C

Power consumption: 70mA Low voltage alarm: support

Preset mode: DEF, VIVID, SUNNY, CLOUDY, LED TR, USR1

Size: 21.8x21.8mm

Weight: 8.7g(excluding bracket)



8.0 SpeedyBee bluetooth module

Support Betaflight configurator

Speedybee App: iOS 10.0+; iPhone 4S, iPad3;

Androd 4.3+

Output power: 0dBM Sensitivity: -94dBM

External interface: BROADCAST SWITCH, TX, RX,

3-5V DC Input, GND

Transmission speed: Bidirectional 1K/S

Bluetooth protocol: Bluetooth Specification V4.0 BLE

Transmission distance: 30 meters

Frequency range: 2400MHz-2483.5MHz (2.4G ISM

Band)

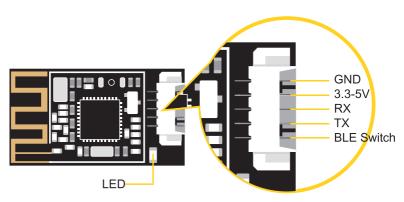
Baud rate: 2400, 4800, 9600, 14400, 19200(default),

28800, 38400, 57600, 76800, 115200, 230400

Working voltage: 3.3V-5.0V Working current: 8.3mA-10mA

Weight: 1.4g

Size: 27*15*4.5mm



LED: Blue and constantly on when being connected. LED does not light means it is not connected.

9.0 110DB BB alarm buzzer

Working voltage: 5V

Standby battery: lipo 4.2V 100mah

Loudness: 110DB Size: 36 * 36mm Weight: 8g

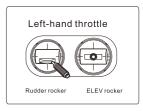
10.0 Motor Unlock/lock

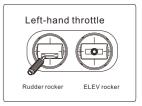
Motor Unlock

Put the throttle rocker at the lowest point, move the rudder rockerto the right and keep it for more than 2 seconds. The blue state indicator is always on, that is unlock the motor.

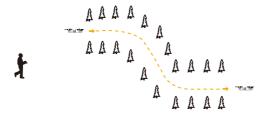
Motor lock

Put the throttle rocker at the lowest point, move the rudder rocker tothe leftmost side, and the red state indicator is always turned on to lock the motor. At this time, pushing the throttle rocker motor upward will not rotate.





11.0 Traversing flight



- 1). Flying is more suitable for experienced pilots.
- 2). During the flight, please keep the flight within the video receiving range (the actual range depends on the flight environment and weather conditions).
- 3). During flight, please avoid crowd, animals and High voltage wires and other obstacles